

PANEVĖŽYS DISTRICT EDUCATION CENTER

COMMUNITY **ALGORITHM** IN A ROBOT'S **BACKPACK**

METODICAL PUBLICATION







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It would be extremely hard to find a field which is not yet been tested or accompanied by robots these days. Robotics is no longer just a theory of the future; it is a part of our present reality. Robotics in education is particularly effective in engaging children who are attracted by smart innovation and a hands-on approach to learning. This is an immersive tool that makes the abstract and complex concepts of science and technology easier to understand, meanwhile developing creative thinking and coordinating teamwork.

Depending on the different interests and learning abilities, each child can be assigned a separate work task: to design, to construct or to code. For teachers it is a great tool for enabling collaborative activities, developing students' leadership skills, teamwork mindset, facilitating socialization.

This methodical publication Community Algorithm In A Robot's Backpack is a source of ideas which came out from the friendship between the educational robots and the Preschool and Primary school teachers and librarians of Panevėžys city and Panevėžys district. We have included practical tasks and tools that we developed and tested together with our students in this robot's backpack. Engaging activities allow children to solve problems in a fun and stress-free way simultaneously performing programming tasks, developing algorithmic thinking, creatively searching for optimal solutions, harmonious communicating and cooperating in the team.

We hope that there will be no shortage of new discoveries and improvisations in your lessons!

Laura Šinkūnienė



Projec 612872-EPP-1-2019-1-IT-EPPKA3-PI-FO	t No RWAR
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	/					А	funny g	ame!
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	Α	В	С	D	Е	F	G	
1								
2								
3								
4								
5								
6								
7								
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			P					

	A funny game!
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	Picture cards
START	FINISH
	Lyrics
If you like this song, give it a clap. If you like this song, give it a clap. If you like this song, sing it all day long. If you like this song, give it a clap.	If you like this song – stamp your feet. If you like this song - stamp your feet. If you like this song, sing it all day long. If you like this song - stamp your feet
If you like this song, shout Hurray! If you like this song, shout Hurray! If you like this song, sing it all day long. If you like this song, shout Hurray!	If you like this song, sing again. If you like this song, sing again. If you like this song, sing it all day long. If you like this song - sing again!

6							F	ind the	way!
			Proje	ect No. 612872-I	EPP-1-2019-1-I	T-EPPKA3-PI-F	ORWARD		21
								R	obot grid
		-	_	-	_	_	_	_	
		Α	В	С	D	E	F	G	
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Example

Find your way by moving from one picture to another, following the example given:

Numerical order		
28 co	OMMUNITY ALGORITHM IN A ROBOT'S BACKPACK	
WORKSHEET	\frown	~
	Group name	
	Organizer	
	Bug fiver	
ΤΔςκ 1	Bug lixer	
Check the pro STARTING POINT. mistakes. DRAW a n	ogram code of the circled number. X marks the ro . When working together, find, mark, and correct number on the sheet using the robot.	bot's t the
	Bugs found:	
Corrected Code:		
TASK 2		
Using the robo ADVANCED. Create SAVE the program. I	ot programming environment CODING , select the e an algorithm for the robot to draw the specified nu DRAW the number on the sheet using the robot.	mode mber.

		Nume	rical order
	Project No. 612872-EPP-1-2019-1-IT	EPPKA3-PI-FORWARD	29
WORKSHEET	\sim		
	Group name		
	Organizer		
	Programmer		
	Bug fixer		
TASK 1			
STARTING POINT. \ mistakes. DRAW a nu	When working togethe mber on the sheet using t	r, find, mark, and g the robot.	I correct the
Corrected Code :	-•	• •	
TASK 2			
Using the robot ADVANCED. Create a SAVE the program. DI	programming environn an algorithm for the rob RAW the number on the	nent CODING , sel ot to draw the spec e sheet using the ro	ect the mode cified number. obot.
~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~			

![](_page_29_Figure_0.jpeg)

		Nume	rical order
	Project No. 612872-EPP-1-2019-1-IT	EPPKA3-PI-FORWARD	31
WORKSHEET	$\sim$		
	Group name		
	Organizer		
	Programmer		
	Bug fixer		
TASK 1			
STARTING POINT. mistakes. DRAW a nu	When working togethe	r, find, mark, and g the robot.	d correct the
		Bugs	found:
Corrected Code :	-•		
TASK 2			
Using the robot ADVANCED. Create a SAVE the program. D	programming environn an algorithm for the rob <b>RAW</b> the number on the	nent <b>CODING</b> , se ot to draw the spe e sheet using the r	lect the mode cified number. obot.

32 COMMUNITY ALGORITHM IN A ROBO	
WORKSHEET	~~
Group name	
Organizer	
Bug fixer	
TASK 1	
STARTING POINT. When working togeth mistakes. DRAW a number on the sheet usi	ed number. X marks the robot's her, find, mark, and correct the ng the robot.
Image: Corrected Code :	Bugs found:
TASK 2 Using the robot programming enviror ADVANCED. Create an algorithm for the ro SAVE the program. DRAW the number on the Company of the program. DRAW the number of the program.	ment <b>CODING</b> , select the mode bot to draw the specified number. he sheet using the robot.

![](_page_32_Picture_0.jpeg)

TASK 3

Glue the numeric code on the sheet of paper next to the drawn number.

TASK 4

Present the group work in a sequence of numbers by finding that number an appropriate location (in an ascending or descending order).

TASK 5

As you work together, **MODIFY** your **NUMBER** on a checkered paper, mark the START POINT (X).

Create an algorithm for the robot to draw the **MODIFIED** number.

**SAVE** the program.

**DRAW** the number on the sheet using the robot.

![](_page_32_Figure_10.jpeg)

![](_page_33_Figure_0.jpeg)

![](_page_34_Figure_0.jpeg)

![](_page_35_Figure_0.jpeg)
00]/		
	Project No. 612872-EPP-1-2019-1-IT-EPPKA3-PI-FORW/	ard 37
ORKSHEET		
	•	
TASK 2		
Correct the	CODE of the drawing so that it can be	drawn by the robot
rite down the <b>C</b>	ODE with the appropriate COLOR and I	DIRECTION arrows
ou can use arro	ow cards).	
	> <hr/>	
The correcte	d code:	
TASK 3		
TASK 3 Using the C	CODING environment select the ADVAN	CED mode.
TASK 3 Using the C Create an RAW the drawin	<b>CODING</b> environment select the <b>ADVAN</b> algorithm for drawing. <b>SAVE</b> the progra	<b>CED</b> mode. am. Set the robot
TASK 3 Using the C Create an RAW the drawin Glue the c	<b>CODING</b> environment select the <b>ADVAN</b> algorithm for drawing. <b>SAVE</b> the progra ng on a sheet of paper. ode and a hand drawn example with a	<b>CED</b> mode. am. Set the robot a code on the she
TASK 3 Using the C Create an RAW the drawin Glue the c ext to the drawin	<b>CODING</b> environment select the <b>ADVAN</b> algorithm for drawing. <b>SAVE</b> the progra ng on a sheet of paper. ode and a hand drawn example with a ng drawn by the robot.	<b>CED</b> mode. am. Set the robot a code on the she
TASK 3 Using the C Create an RAW the drawin Glue the c ext to the drawin	<b>CODING</b> environment select the <b>ADVAN</b> algorithm for drawing. <b>SAVE</b> the progra ng on a sheet of paper. ode and a hand drawn example with a ng drawn by the robot.	CED mode. am. Set the robot a code on the she NOTES
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TASK 3 Using the C Create an RAW the drawin Glue the c ext to the drawin	CODING environment select the ADVAN algorithm for drawing. SAVE the progra ng on a sheet of paper. ode and a hand drawn example with a ng drawn by the robot.	CED mode. am. Set the robot a code on the she NOTES



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	Project No. 612872-EF	PP-1-2019-1-IT-EPPKA3-PI-FORWAF	RD 39
ORKSHEET			
	•		
TASK 2			
Correct the	CODE of the drawi	ng so that it can be d	rawn by the robot
rite down the <b>C</b>	ODE with the appro	priate COLOR and D	<b>IRECTION</b> arrows
ou can use arro	w cards).		
Î 🚺 🌈	· <		
The correcte	d code:		
•			
TASK 3			
TASK 3 Using the <b>C</b>	<b>ODING</b> environmer	nt select the <b>ADVANC</b>	ED mode.
TASK 3 Using the <b>C</b> Create an <b>RAW</b> the drawin	<b>ODING</b> environmer algorithm for drawir ng on a sheet of pap	nt select the <b>ADVANC</b> ng. <b>SAVE</b> the program	ED mode. m. Set the robot
TASK 3 Using the <b>C</b> Create an <b>RAW</b> the drawin Glue the co	<b>ODING</b> environmer algorithm for drawir ng on a sheet of pap ode and a hand dra	nt select the <b>ADVANC</b> ng. <b>SAVE</b> the program per. awn example with a	ED mode. m. Set the robot code on the she
TASK 3 Using the <b>C</b> Create an <b>RAW</b> the drawin Glue the ca ext to the drawin	<b>ODING</b> environmer algorithm for drawir ng on a sheet of pap ode and a hand dra ng drawn by the rob	nt select the <b>ADVANC</b> ng. <b>SAVE</b> the program per. awn example with a ot.	ED mode. m. Set the robot code on the she
TASK 3 Using the C Create an RAW the drawin Glue the creater Share the drawin	<b>ODING</b> environmer algorithm for drawir ng on a sheet of pap ode and a hand dra ng drawn by the rob	nt select the <b>ADVANC</b> ng. <b>SAVE</b> the program per. awn example with a ot.	ED mode. m. Set the robot code on the she
TASK 3 Using the C Create an RAW the drawin Glue the ca ext to the drawin	<b>ODING</b> environmer algorithm for drawir ng on a sheet of pap ode and a hand dra ng drawn by the rob	nt select the <b>ADVANC</b> ng. <b>SAVE</b> the program per. awn example with a ot.	ED mode. m. Set the robot code on the she NOTES
TASK 3 Using the C Create an RAW the drawin Glue the created axt to the drawin	<b>ODING</b> environmer algorithm for drawir ag on a sheet of pap ode and a hand dra ag drawn by the rob	nt select the <b>ADVANC</b> ng. <b>SAVE</b> the program per. awn example with a ot.	ED mode. m. Set the robot code on the she NOTES
TASK 3 Using the C Create an RAW the drawin Glue the creater ext to the drawin	<b>ODING</b> environmer algorithm for drawir ng on a sheet of pap ode and a hand dra ng drawn by the robe	nt select the <b>ADVANC</b> ng. <b>SAVE</b> the program per. awn example with a ot.	ED mode. m. Set the robot code on the she NOTES



	RoboART - drawing while p	programming!
	Project No. 612872-EPP-1-2019-1-IT-EPPKA3-PI-FORWARD	41
WORKSHEET		
	•	
TASK 2		
Correct the CO	<b>DE</b> of the drawing so that it can be drawn	by the robot.
vrite down the COD you can use arrow c	cards).	STION arrows
	 ۲	
The corrected co	ode:	
•		
TASK 3		
Using the COD	DING environment select the ADVANCED	mode.
Create an algo DRAW the drawing o	orithm for drawing. <b>SAVE</b> the program. S on a sheet of paper.	et the robot to
Glue the code next to the drawing c	e and a hand drawn example with a code drawn by the robot.	e on the sheet
		NOTES
	•	NOTES



ω	Project No. 612872-EPP-1-2019-1-IT-EPPKA3-PI-FORWARD	43
WORKSHEET		
	•	
TASK 2		
Correct the C	ODE of the drawing so that it can be drawn	h by the robot.
Vrite down the CO	DE with the appropriate COLOR and DIRE	CTION arrows
The corrected	code:	
TASK 3		
Using the CC	DDING environment select the ADVANCED	mode.
Create an al	lgorithm for drawing. SAVE the program. S	Set the robot
RAW the drawing	g on a sheet of paper.	
	de and a hand drawn example with a code	e on the she
Glue the coo		
Glue the coo next to the drawing	g drawn by the robot.	
Glue the coo lext to the drawing	g drawn by the robot.	NOTES
Glue the coo ext to the drawing	g drawn by the robot.	NOTES
Glue the coo ext to the drawing	g drawn by the robot.	NOTES
Glue the coo next to the drawing	g drawn by the robot.	
ue the coo ne drawing	g drawn by the robot.	NOTES
Glue the coo ext to the drawing	g drawn by the robot.	NOTES



	L		RoboART -	- drawing	while	programming!
		Project No. 6128	372-EPP-1-2019-1-I	T-EPPKA3-PI-FC	RWARD	45
WORKS	HEET					
	TASK 4-b	•				
•	Using the CODIN	IG environi	ment select	the ADVA	NCED	mode.
progra	Create an algorit Im. Set the robot	hm for drav to <b>DRAW</b> t	wing you ge the drawing	et from an y on a she	other te et of pa	eem. <b>SAVE</b> the per.
	↓ ☆ <	à				
T	he code:					
	TASK 5					
drawi	Glue the code angs drawn by the	and a hand robot.	d drawn ex	ample on	the sh	neet next to the
	Present your dra	wings to ot	her teems	at <b>RoboA</b> i	r <b>t</b> galle	ry.
	QUESTIONS?					
	How did you de	cide what	role vou wa	uld nlav ir	the an	0UD2
•	Why did you ha	we to chan	ide the drar	bic dictati	on code	oup: ≏2
•	How was the a	ranhic dicta	ation code o	lifferent fr	on the	rohot code?
▼		aprile diole	he code for	the robot	immed	iatelv?
•	Where did you	need the h	elp the mo	st? Who h	elped?	
Ŧ						









- How did you succeed to decode the robots' path algorithms and to program the robot?
- How will this lesson be useful in the future?
- What did you learn from working together with a friend?

Notes

The first example on the worksheet can be done together to make sure that all students understand what needs to be done. In the next lesson, the students will learn to group objects made of the same material, name the properties (attributes) of materials, group materials according to their properties, find out under what conditions the properties of materials can change (heating, melting, burning).

#### What is it made of? 50 COMMUNITY ALGORITHM IN A ROBOT'S BACKPACK WORKSHEET <u>N</u>0. 7 <u>6</u> Ч 4 ω Ņ <del>. `</del> Analyze the Mind Designer bot path algorithm **★** → **↑ + ↓** STUDENTS' NAMES: Consult each other and write down your guess, Which grid cell will the How many correct guesses in robot go to? e.g. C3. total? If your guess is correct, Program the robot. mark it 🕇 coordinates of the cell Read the question in Which number did you circle the most? (eg C3) that contains Write down the the answer. that box. correctly right from the first time? Circle the containing the answer. Program the robot to program the robot Did you manage to correct number. stop at the box ---N N N Ν Ν N N ω ω ω ω ω ω ω in that box next to the Write the letter that is Place the robot in the "Start" box. picture.

			Proje	ect No. 61	2872-EPP	-1-2019-1-	T-EPPKA	3-PI-FORWARD	
	7.	<u>ල</u>	ى. ب	. <del>4</del>	ω	Ņ	<u>.</u>	No.	
	↑ ← ↑ → ↑ ← ↑			↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑	+ + + + + +	<b>↓ → </b>	•	Analyze the Mind Designer bot path algorithm	
How many correct guesses in total?	A1	Α4	D2	5	Щ	E4	B2	Consult each other and write down your guess, e.g. C3.	Which grid cell will the robot go to?
								If your guess is correct, mark it +	Program the robot.
Which number did you circle the most?	E2	C1	F4	A2	D3	Ξ	<b>B</b> 4	Write down the coordinates of the cell (eg C3) that contains the answer.	Read the question in that box.
	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	1 2 3	Did you manage to program the robot correctly right from the first time? Circle the correct number.	Program the robot to stop at the box containing the answer.
	ES	ק	C		A	m	т	Place the robot in t "Start" box.	Write the letter that in that box next to t picture.

#### What is it made of?



COMMUNITY ALGORITHM IN A ROBOT'S BACKPACK





## What is it made of?

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COMMUNITY ALGORITHM IN A ROBOT'S BACKPACK

## Picture cards





What is it made of?						
56 COMMUNITY ALGORITHM IN	А ROBOT'S BACKPACK					
Question cards						
Which object is made of only sand and chalk?	Which item does not use metal, ceramics, water, or wool in its production?					
Which object is made only of metal?	Which item does not use glass, rubber, wood, metal, food, or plastic?					
Which object is made only using glass?	In the production of which item, glass is one of the components?					

	What is it made of?
Project No. 612872-EPP-7	1-2019-1-IT-ЕРРКАЗ-PI-FORWARD 57
	Question cards
Which item is made of metal and rubber?	START



Cal	$\left\lfloor C n \right\rfloor$	lations.	Concept	s
Cal	LCul	Latrons.	Concept	-

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Number grid

	Α	В	С	D	E	F
1	8	15	1		36	
2	7		24	45	3	10
3	4	21		30		6
4		2	18	5	9	60

Mood meter

Enraged	Furious	Frustrated	Shocked	Μ	Surprised	Upbeat	Motivated	Ecstatic
Livid	Frightened	Nervous	Restless	0	Hyper	Cheerful	Inspired	Elated
Fuming	Apprehensive	Worried	Annoyed	0	Energized	Lively	Optimistic	Thrilled
Repulsed	Troubled	Uneasy	Peeved	D	Pleasant	Joyful	Proud	Blissful
Μ	0	0	D	Μ	E	T	E	R
Disgusted	Disappointed	Glum	Ashamed	E	Blessed	At Ease	Content	Fulfilled
Mortified	Alienated	Мореу	Apathetic	Т	Humble	Secure	Chill	Grateful
Embarrassed	Excluded	Timid	Drained	E	Calm	Satisfied	Relaxed	Carefree
Alone	Down	Bored	Tired	R	Relieved	Restful	Tranquil	Serene
Mood meter	link <u>https</u>	://eenhigby	weebly.co	om/mood-	<u>meter.html</u>			

# Calculations. Concepts COMMUNITY ALGORITHM IN A ROBOT'S BACKPACK 60 Task cards TASK 1 Working individually, according to the given description, perform the calculations. Compare answers with your group mates. Using arrow cards make an algorithm - the path for the robot to reach the right number. The units digit is the product of 2 and 3, the tens digit is the quotient of 27 and 9. TASK 2 Working individually, according to the given description, perform the calculations. Compare answers with your group mates. Using arrow cards make an algorithm - the path for the robot to reach the right number. The tens digit is the difference of 19 and 15, the units digit is the sum of 3 and 2. TASK 3 Working individually, according to the given description, perform the calculations. Compare answers with your group mates. Using arrow cards make an algorithm - the path for the robot to reach the right number. The number is even. The tens digit is 2 times smaller than the units digit.



### Calculations. Concepts

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COMMUNITY ALGORITHM IN A ROBOT'S BACKPACK



#### Task cards

## TASK 7

Working individually, according to the given description, perform the calculations. Compare answers with your group mates. Using arrow cards make an algorithm - the path for the robot to reach the right number.

The quotient of the difference between the largest three-digit number and the smallest two-digit number and the number 90.

## TASK 8

Working individually, according to the given description, perform the calculations. Compare answers with your group mates. Using arrow cards make an algorithm - the path for the robot to reach the right number.

A two-digit number in which both digits are odd numbers.

## TASK 9

Working individually, according to the given description, perform the calculations. Compare answers with your group mates. Using arrow cards make an algorithm - the path for the robot to reach the right number.

A number that is obtained by adding two equal odd two-digit numbers. .





## Angles

Project No. 612872-EPP-1-2019-1-IT-EPPKA3-PI-FORWARD

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## Number grid



Mood meter

Enraged	Furious	Frustrated	Shocked	Μ	Surprised	Upbeat	Motivated	Ecstatic
Livid	Frightened	Nervous	Restless	0	Hyper	Cheerful	Inspired	Elated
Fuming	Apprehensive	Worried	Annoyed	0	Energized	Lively	Optimistic	Thrilled
Repulsed	Troubled	Uneasy	Peeved	D	Pleasant	Joyful	Proud	Blissful
Μ	0	0	D	Μ	E	Т	E	R
Disgusted	Disappointed	Glum	Ashamed	E	Blessed	At Ease	Content	Fulfilled
Mortified	Alienated	Мореу	Apathetic	Т	Humble	Secure	Chill	Grateful
Embarrassed	Excluded	Timid	Drained	E	Calm	Satisfied	Relaxed	Carefree
Alone	Down	Bored	Tired	R	Relieved	Restful	Tranquil	Serene
ood meter	link <u>https</u>	://eenhigby	.weebly.c	om/mood-i	meter.html			







Numerical phenomena

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Number grid

				•		
	Α	В	С	D	E	F
1	8	15	1		36	
2	7		24	45	3	10
3	4	21		30		6
4		2	18	5	9	60

Mood meter

Enraged	Furious	Frustrated	Shocked	Μ	Surprised	Upbeat	Motivated	Ecstatic			
Livid	Frightened	Nervous	Restless	0	Hyper	Cheerful	Inspired	Elated			
Fuming	Apprehensive	Worried	Annoyed	0	Energized	Lively	Optimistic	Thrilled			
Repulsed	Troubled	Uneasy	Peeved	D	Pleasant	Joyful	Proud	Blissful			
Μ	0	0	D	Μ	E	Т	E	R			
Disgusted	Disappointed	Glum	Ashamed	E	Blessed	At Ease	Content	Fulfilled			
Mortified	Alienated	Мореу	Apathetic	Τ	Humble	Secure	Chill	Grateful			
Embarrassed	Excluded	Timid	Drained	E	Calm	Satisfied	Relaxed	Carefree			
Alone	Down	Bored	Tired	R	Relieved	Restful	Tranquil	Serene			
ood meter	ood meter link <u>https://eenhigby.weebly.com/mood-meter.html</u>										








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COMMUNITY ALGORITHM IN A ROBOT'S BACKPACK



#### Game — The Train of Fear

Imagine that you alone have to go on a train trip at midnight and come home from a station on foot.

Choose a moment when fear overcomes you (when you want to stop and discontinue travel), then come and stand up near selected card in a scale of fear.

(The "Fear Train" situation cards are read one by one and pinned on the stretched rope using the pins. The text should be read slowly, giving the time for students to assess their fear level and choose a place on the "fear scale".)

- 1. I'm alone on a platform at midnight and waiting for a train...
- 2. I get in the train and sit solitary...
- 3. At the next stop all passengers get off, I'm staying alone...
- 4. I get off, it is dark around, no living spirit...
- 5. I hear steps behind my back, I'm going to go faster...
- 6. Someone, who follows me, also starts going faster...
- 7. I go to the next side of the road, someone follows me...
- 8. I look back and see that husky man is following me...
- 9. I'm almost running, the man comes up and touches my shoulder...
  - Maybe, somebody wants to finish his/her journey right now?
  - Perhaps there are passengers who want to change their choice?

NOTES

Here is proof that we all are different and our reactions are different, too. There are people who would never travel at night, there are people who will travel by train, but when they go off, they won't go on foot and so on. Different people different moments sensation of fear.



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Cards — The Train of Fear

# I'm alone on a platform at midnight and waiting for a train...

# I get in the train and sit solitary...

COMMUNITY ALGORITHM IN A ROBOT'S BACKPACK

#### Cards — The Train of Fear

# At the next stop all passengers get off, I`m staying alone...

I get off, it is dark around, no living spirit...

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#### Cards — The Train of Fear

# I go to the other side of the road, someone follows me...

# I look back and see that husky man is following me...



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Cards — The Train of Fear

# I'm almost running, the man comes up and touches my shoulder...





- Everyone is responsible both for her/himself and for the whole team.
- Everyone helps the team to complete the task.
- The work is presented by the whole group.



The Algorithm of Fear	
82 COMMUNITY ALGORITHM IN Task cards — Suitcases	I A ROBOT'S BACKPACK
TRAVEL ALONE	TRAVEL WITH FRIEND
I AM DOING THAT CONSTANTLY	I AM DOING THAT FIRST TIME
WELL KNOWN TRAVEL GOAL	UNKNOWN TRAVEL GOAL
OTHER TYPE OF TRANSPORT	



Situation cards are shuffled and placed in any order. The robot only drives through empty cells. The sorted card is "transported" by sticking it with an adhesive rubber to the robot.

- What helps to manage fear? (discussion, possible conclusions)
  - It is safer to travel with a friend.
  - When I have tools to help me in a critical moment, I gain courage.
  - It is very important to have a purpose (for example, I am going to visit
  - a sick friend and maybe this is the last chance to meet him).



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Task "Algorithm for overcoming fear"

Working together and following the given rules, create **THE ALGORITHM FOR OVERCOMING FEAR**:

- In the robot grid find the cards to help you cope with fear in class and stick a green sticker on them.
- Use the arrows to write the shortest path and pass it with the robot (all boxes on the robot's path must be marked with stickers).
- Comment your choice.

# THE ALGORITHM FOR OVERCOMING FEAR:

### RULES:

- Work is shared by all team members.
- The section of the road to the selected card is programmed by each team member.
- Everyone is responsible both for her/himself and for the whole team.
- Everyone helps the team to complete the task.
- The work is presented by the whole group.



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COMMUNITY ALGORITHM IN A ROBOT'S BACKPACK



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I`m not asking because others think that I am know-nothing	Teachers and parents are waiting / hoping for the best results, I can't disappoint them
In the group, we decide how we will achieve the learning goals	Everybody obey / have to agree with group leader
I can help others; By helping friends - I learn better	I am responsible only for myself in a team

		The Algorithm of Fear
U	Project No. 612872-EPP-	-1-2019-1-IT-EPPKA3-PI-FORWARD 87
	Cards	for the ALGORITHM FOR OVERCOMING FEAR ta
Importar comm team g	nt the on oal	In a success or failure case I am responsible team member
When I am a speaking / in public checking advise) wi frien	afraid in answer c, I'm c (ask ith my d	
		Note

The Algorithm of Fear	
88 COMMUNITY ALGORITHM IN	а ROBOT'S BACKPACK
Užduoties "Baimės nugalėjimo algoritmas" kortelės	5
Studying alone	I feel safer when I study with a friend (in a group)
Everything have to find out myself	I can and am not afraid to ask friends or teachers for help
Mistakes will determine my evaluation	I am not afraid to make mistakes — my group mates will give me advice; Mistakes help us improve





	Drojost No. 640870 EDD 44		orithm of Fear
ω	Project No. 612872-EPP-1-	2019-1-II-EPPKA3-PI-FORWARD	9⊥ Travel Diar
I THROW AWAY or I RECYCLING:	FEEDBACK: I TAKE IT NOW: I SAVE IT FOR THE FUTURE:	WRITE down the CODE for Algorithm For Overcoming Fear Use arrows	
(NAME) <b>Travel Diary</b>	The Algorithm of Fear	HE ALGORITHM OF FEAR IN THE LESSON Vorking in a team, you figured out and ound ways to overcome fear in class. NRITE down at least <b>3 ways</b> that help you eel safer in the class:	
<ul> <li>FEAR.</li> <li>FEAR.</li> <li>STEPS:</li> <li>1. I'm alone on a platform at midnight and waiting for a train.</li> <li>2. I get in the train and sit solitary.</li> <li>3. At the next stop all passengers get off, I'm staying alone.</li> <li>4. I get off, it is dark around, no living spirit.</li> <li>5. I hear steps behind my back, I'm going to go faster.</li> </ul>	THE TRAIN OF FEAR Objective: Think about that all feel different and not everyone wants to take a risk. PROCESS: Imagine, that you alone have to go on a train trip at midnight and come home from a station on foot. Choose a moment when fear overcomes you, then stand up near selected card in a SCALE OF	Solitoses	
MARK where you would like to get off. WHY?	<ul> <li>6. Someone, who follows me, also starts going faster.</li> <li>7. I go to the other side of the road, someone is following me.</li> <li>8. I look back and see that husky man follows me.</li> <li>9. I'm almost running, the man comes up and touches my shoulder.</li> </ul>	UITCASES Ibjective: Working in a team think about assons, which make feel safe on a trip. ASK: Create safe and unsafe travel resentation. ut cards into two suitcases: ut cards into two suitcases: Suitcase "Trip without stress"	ARDS: Well known travel goal / * I am doing that Sonstantly / * flashlight / * night / travel alone / * smartphone / *day / I am doing that first time / * travel with iend / * unknown travel goal / other type of transport /

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### RESOURCES

#### **ILLUSTRATIONS**

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Available programming modes : **BASIC** (line length 15 cm, turning angle 90°) and ADVANCED (line length and turn angle can be adjusted, procedures can be created).





COMMUNITY ALGORITHM IN A ROBOT'S BACKPACK

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